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2014 International Workshop on Electronics and Communications Program Overview

Monday October 27th, 2014			
09:15-09:30	Registration (The Second Floor Lobby)		
09:30-10:05 Open Ceremony (C216, Chair: Prof. Jin Pan, UESTC, China)			
09:30-09:40	Welcome Speech: Prof. Jun Hu, School of EE, UESTC, China		
09:40-09:50	Speech from Korea representative: Prof. Ho-Youl Jung, Yeungnam University, Korea		
09:50-10:00	Speech from Japan representative : Prof. Fumiyuki Adachi, Tohoku University, Japan		
10:00-10:05	Technical Program Chair Speech: Dr. Xingang Liu, UESTC, China		
10:05-10:35	Keynote Speech I: Prof. Kai Kang, UESTC, China (C216)		
10:35-11:00	Group Photo & Coffee Break		
11:00-11:30	Keynote Speech II: Prof. Ho-Youl Jung, Yeungnam University, Korea (C216)		
11:30-12:00	Keynote Speech III: Prof. Akinori Ito, Tohoku University (C216)		
12:00-13:50	Lunch (FuRong Restaurant)		
13:50-15:50	<table border="0" style="width: 100%;"> <tr> <td style="width: 50%; text-align: center;">WEC2014 Oral Session I (C204, Chair: Prof. Jinfeng Hu, UESTC)</td> <td style="width: 50%; text-align: center;">WEC2014 Oral Session II (C218, Chair: Prof. Zongjie Cao, UESTC)</td> </tr> </table>	WEC2014 Oral Session I (C204, Chair: Prof. Jinfeng Hu, UESTC)	WEC2014 Oral Session II (C218, Chair: Prof. Zongjie Cao, UESTC)
WEC2014 Oral Session I (C204, Chair: Prof. Jinfeng Hu, UESTC)	WEC2014 Oral Session II (C218, Chair: Prof. Zongjie Cao, UESTC)		
15:50-16:05	Coffee Break (The Second Floor Lobby)		
16:05-18:05	<table border="0" style="width: 100%;"> <tr> <td style="width: 50%; text-align: center;">WEC2014 Oral Session III (C204, Chair: Prof. Jinfeng Hu, UESTC)</td> <td style="width: 50%; text-align: center;">WEC2014 Oral Session IV (C218, Chair: Prof. Zongjie Cao, UESTC)</td> </tr> </table>	WEC2014 Oral Session III (C204, Chair: Prof. Jinfeng Hu, UESTC)	WEC2014 Oral Session IV (C218, Chair: Prof. Zongjie Cao, UESTC)
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18:30-20:30	Banquet (HeKangJiaYun Restaurant)		

Tuesday October 28th, 2014	
09:30-12:00	Visiting the Old Campus of UESTC
12:00-13:30	Lunch (Hotel of UESTC)
14:30-15:45	Professors Meeting in New Campus (C218); Free Time Visiting for Students
15:45-17:45	Visiting the New Campus of UESTC
18:00-20:30	Dinner (FuRong Restaurant)

The Impact of Channel Selection Algorithms on Transport Protocols in CRAHN

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Abstract— The cognitive radio adhoc network is designed to cater the spectrum scarcity by increasing the spectrum utilization. It allows unlicensed user to employ it when it is free. To order to maintain end-to-end reliability the transport protocol adjusts the source transmission rate by adapting to the congestion on the route. A number of new transport protocols were proposed for cognitive radio in the literature. This paper studies three transport protocols: TCP, TFRC and TFRC-CR for cognitive radio networks with respect to different channel selection policies. The sequential and random channel selection algorithms are used to analyze the overall performance of the transport protocols. Extensive set of simulations is carried out in NS-2. To evaluate the performance of these transport protocols we used average throughput and end-to-end delay as metrics. The empirical results highlight suggestive outcomes. The transport protocols with random channel selection policy perform better than the sequential channel selection policy.

Keywords—TCP, TFRC, TFRC-CR, CRAHN, CW

I. INTRODUCTION

The increasing use of unlicensed band in the wireless medium has resulted in growing congestion and thus spectrum scarcity. The Federal communications Commission (FCC) pointed earlier to use the additional spectrum for unlicensed operations [1]. Latterly, the abandon frequency ranges ascribed to the analog to digital television transition for use by unlicensed operators [2]. This permit devices to sense channels and transmit opportunistically. These devices are enabled with cognitive radio (CR) capabilities. Therefore, it allows devices to sense the spectrum utilization, select the best available channel and share the available spectrum resource among other devices [3]. Although, The adaptivity of CR in ad hoc networks (CRAHNs) is not easy, with the challenges posed by the limited spectrum knowledge at the individual nodes and the decentralized operation [4].

The Cognitive radio ad hoc networks (CRAHNs) [4,5] are usually composed of two kinds of users: CR users and primary users (PUs). The PUs are the license users. However, CR user opportunistically accesses the licensed spectrum holes. The CRAHN facilitates the researchers to ample the wide range of parameters, such as power and spectrum, channel bandwidth and frequency, use custom-designed or existing spectrum selection and sharing

policies and model accurately the activity of the PUs and CR users.

A significant number of studies are carried out on transport layer in wireless networks over the past decade. However, transport protocols for CR are just coming into the existence. The suitability of TCP for CR networks, given its widespread use, has been explored in [3,6-9]. The TCP Friendly Rate control (TFRC) protocol [10], employs equation based congestion control in unicast traffic. Its focus on providing a stable throughput, as opposed to the sudden variations caused by the additive increase multiplicative decrease behavior of TCP. The TCP Friendly Rate Control for Cognitive Radio (TFRC-CR) [11], proposed the first equation-based transport protocol. It allows immediate changes in the transmission rate based on the spectrum-related changes in the network environment. Moreover, it does not assume any cross-layer feedback or input from intermediate nodes. The main features of TFRC-CR are as follows. According to the FCC regulations, the protocol is integrated with the spectrum data bases. Therefore, completely eliminated any kind of feedback from the intermediate nodes or from lower layers. The proposed protocol polls at least once in every 60 seconds as specified in the FCC regulations. The TFRC-CR can distinguish between congestion and spectrum change. Thus, the transmission rate is never reprimanded. They modified the TFRC rate control equation by amending the loss event interval. As a consequence, it makes use of the bandwidth more efficiently with the help of higher and accurate sending rate. Hence, attained better throughput.

In CR networks, there is no assurance that a spectrum band will be vacant during the whole communication of CR user. If PU becomes active the CR user needs to find the next vacant channel or remain idle until PU finish its transmission. Therefore, the CR user performance solely dependent on the channel selection policy and algorithm. Moreover, in channel selection, the next vacant channel for communication should not interfere with the channel currently occupied by the PU. If the channel selection algorithm is suboptimal, it severely degrades the performance of the system. In this paper, we are evaluating the impact of different channel selection algorithm on the performance of the end-to-end protocol. According to the best of our knowledge this is the first study to see the impact on cross layer.

The rest of the paper is organized as follows. Section II presents the simulation environment. Section III reveals

the simulation modeling and analysis in detail. Finally, section IV concludes the paper.

II. SIMULATION ENVIRONMENT

A. Simulation Tool

A substantial set of simulations is conducted in NS-2.33 [12]. We configure CRAHN in NS-2.33. The default simulation parameter values used are given below in Table I.

TABLE I. SIMULATION PARAMETERS

Radio propagation model	Two Ray Ground
Channel Type	Wireless Channel
Network Interface Type	Wireless Phy
Mac Type	802.11
Antenna Model	Omni Antenna
Routing Protocol	AODV
Transport Layer	TFRC-CR/TFRC/TCP
Number of Nodes	50
Queue Length	500
Cognitive Radio Model	CRAHN
Simulation Time	200 s

B. Evaluation Metrics

The evaluation parameters used are listed below.

i) Average Throughput

The total number of packets successfully received, divided by the total transmission time. The average throughput can be calculated by using the equation below.

$$\text{Average Throughput} = \frac{\text{Number of Packets Received}}{\text{Simulation Time}} \quad (1)$$

ii) Average End to End Delay

The average time taken by a data packet to arrive in the destination. We have calculated end-to-end delay as follows

$$D_A = T_{RP} - T_{SP} \quad (2)$$

Where

$$D_A = \text{Delay}$$

$$T_{RP} = \text{Time of received packet}$$

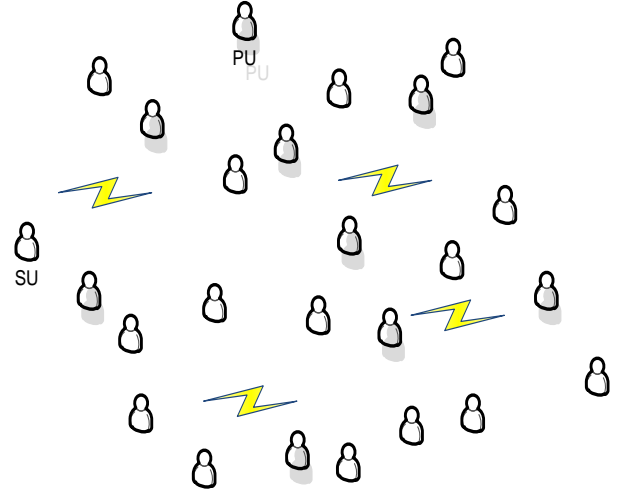
$$T_{SP} = \text{Time of Packet sent}$$

The average end-to-end delay is calculated by summing up all the delays divided by the number of packets received.

III. SIMULATION MODELING AND ANALYSIS

The network model presented in Fig 1. It contains 50 SUs and 20 PUs placed randomly. The PUs activity is independent and random over the course of simulation time. We conducted all the experiments on multihop CRAHN. In this way, there are one or more intermediate nodes along the path that receive and forward packets via wireless link. The CRAHN environment is based on

eleven channels. All the channels have homogenous capacity. When the PU is sensed to be active on the current channel, the spectrum decision block check for spectrum policy and choose the next channel to be used by the CR users. In case of PU detection, the channel



Random Network Model of 20 PUs and 50 SUs

Fig. 1. Network Model

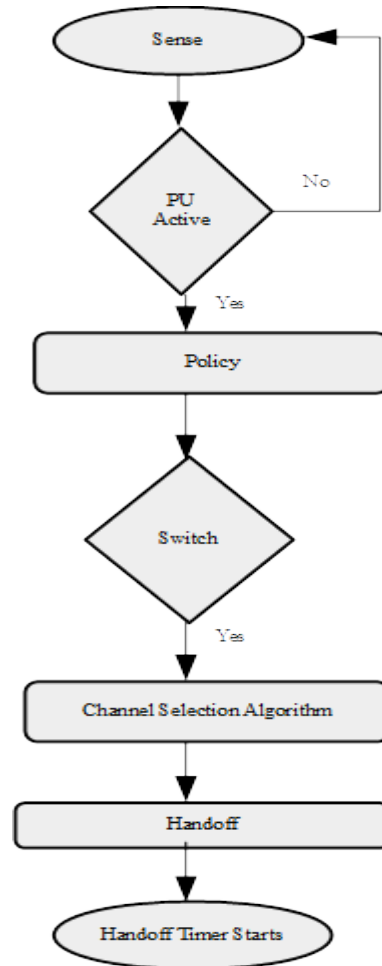


Fig. 2. Channel Selection flowchart

selection policy always looks for next vacant channel, i.e. always switch.

In this policy, the CR user immediately vacates the current channel and moves to the other available channel otherwise pause the transmission. In order to do the channel selection, we used two channel allocation algorithms namely random and sequential. In the random allocation scheme, the CR user chooses randomly among the available channels. In case of sequential scheme, the CR users visit all the available channels by round robin algorithm.

We are interested to see how the transport protocol reacts according to the channel selection policy. The Fig 2 shows the channel selection flowchart. When PU is sensed active, the CR user must vacate the current channel. Furthermore, it gets a new channel to switch according to the channel selection algorithm. The new channel is sensed for any PU activity. If the channel is free, the handoff process is initiated. During the handoff process, the CR user is not permitted to perform any communication.

The Fig 3 and Fig 4 depict the throughput of TFRC-CR, TFRC and TCP when selection policy is sequential and random respectively. It clearly shows that TCP performance is worse among the others. The self-clocking mechanism of TCP is highly susceptible to the observed round trip time (RTT). With the periodic interruptions caused by the PUs appearance, this mechanism by itself is unable to distinguish true congestion from PU induced spectrum changes. In addition, the dependence on ACK timing is aggravated in CR networks owing to the fact that, nodes pause their transmission when they are engaged in sensing or channel switching. This results in a varying RTT estimate and consequently make self clocking mechanism futile. Moreover, the additive increase/multiplicative-decrease (AIMD) algorithm, performs the rate control in TCP combines linear growth of the congestion window (CW) size. In this way, during the congestion avoidance phase an exponential reduction takes place. In the congestion avoidance phase, the CW is increased by one segment on each RTT. This conservative approach is scanty for CR networks since the spectrum opportunity is often lost before the CW has amplified to half the segments [3]. The TFRC also assumes that dropped packets occur due to the congestion only and consequently it reduces the sending rate at source. Moreover, in CR networks, the disparity in the sampling of TFRC can be wider as PU activity and spectrum availability changes and subsequently affect the sending rate. TFRC-CR high throughput rate at the high PU activity scenario is a result of slowing down the sending rate. Also, it avoids the excess and eventually lost packets that are sent in TCP and TFRC [11]. The empirical results shows, random selection policy performs better and consistent than the sequential one.

Table II illustrates the average delay with respect to the simulation time for the round robin and random selection policies. TFRC-CR shows better results than the TFRC and TCP. TCP performance is the execrable among all transport protocols. The TFRC-CR accomplishes well

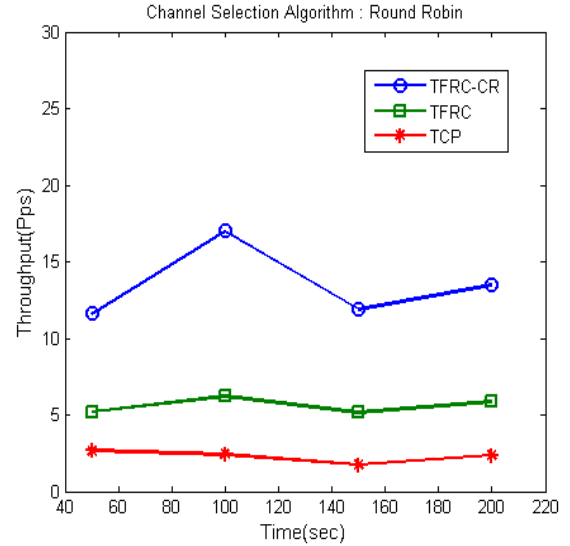


Fig. 3. Time vs Throughput

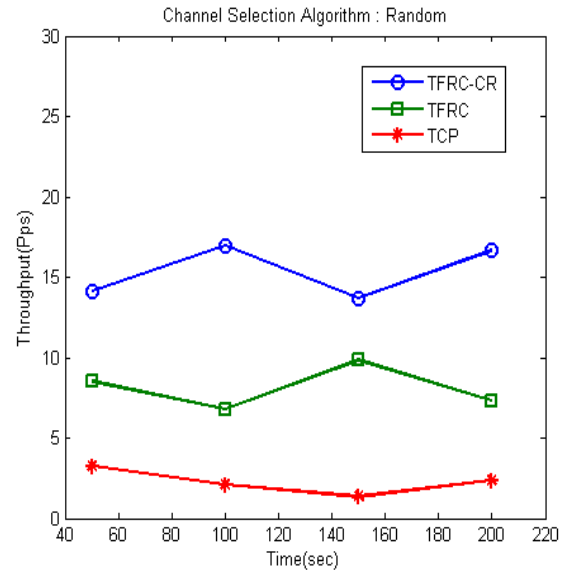


Fig. 4. Time vs Throughput

Table II. Time vs Delay

Channel Selection Policy	Delay(ms)			
	Time(sec)	TFRC-CR	TFRC	TCP
<i>Round Robin</i>	50	304.85	286.45	1036.58
	100	271.77	250.15	1035.51
	150	256.15	226.51	1011.67
	200	241.44	223.51	1036.45
<i>Random</i>	50	247.67	285.85	1136.53
	100	234.64	267.67	1013.02
	150	226.99	222.15	1041.46
	200	221.33	221.20	1021.06

with random selection. The random channel selection algorithm is able to find the next vacant channel in lesser time. Therefore, attains better delay and throughput.

IV. CONCLUSION

In this paper, we studied three transport protocols, namely, TCP, TFRC and TFRC-CR with different channel selection algorithms. We aimed to investigate the transport protocols in order to provide efficient utilization of available spectrum and to increase the overall performance of CR users without the interference of PU. It has been observed that the impact of the interruptions caused by the activity of the PU degrades the transport protocol and consequently reduced the transmission rate. The channel selection policy has a key role in finding the next vacant channel within the shortest time to maintain the overall performance of the CR users. We evaluated two simple channel selection policies, i.e. sequential and random policy. Simulation results depicted that the transport protocols with random channel selection policy perform better than the sequential channel selection policy algorithms. So, they achieved higher packets per second with lesser end-to-end delay.

The efficient channel selection policy and reliable transport protocols are not fully explored in CRAHN. In this context, it can be an open research challenge.

ACKNOWLEDGMENT

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